

**Compatibility table**

	Reference operations (page <a href="#">177</a> )	+/- speed (3) (page <a href="#">194</a> )	Preset speeds (page <a href="#">189</a> )	PID regulator (page <a href="#">222</a> )	Traverse control (page <a href="#">256</a> )	JOG operation (page <a href="#">187</a> )	Reference switching (page <a href="#">176</a> )	Skip frequency (page <a href="#">192</a> )	Brake logic control (page <a href="#">206</a> )	Auto DC injection (page <a href="#">185</a> )	Catch on the fly (page <a href="#">267</a> )	Output contactor command (page <a href="#">235</a> )	DC injection stop (page <a href="#">182</a> )	Fast stop (page <a href="#">182</a> )	Freewheel stop (page <a href="#">182</a> )	+/- speed around a reference (page <a href="#">196</a> )	High speed hoisting (page <a href="#">216</a> )	Load sharing (page <a href="#">130</a> )	Positioning by sensors (page <a href="#">239</a> )
Reference operations (page <a href="#">177</a> )			↑	● (2)		↑	↑	↑											
+/- speed (3) (page <a href="#">194</a> )					●	●	↑	↑											
Preset speeds (page <a href="#">189</a> )	←					↑	↑	↑											
PID regulator (page <a href="#">222</a> )	● (2)				●	●	↑	↑	●								●	●	●
Traverse control (page <a href="#">256</a> )		●		●	●	●	↑	↑									●	●	
JOG operation (page <a href="#">187</a> )	←	●	←	●	●			↑	●	←							●	●	
Reference switching (page <a href="#">176</a> )	←	←	←	←	←			↑									↑		
Skip frequency (page <a href="#">192</a> )	↑	↑	↑	↑	↑	↑	↑										↑		
Brake logic control (page <a href="#">206</a> )			●		●						●	●	●						
Auto DC injection (page <a href="#">185</a> )					↑								↑	↑					
Catch on the fly (page <a href="#">267</a> )								●											
Output contactor command (page <a href="#">235</a> )								●											
DC injection stop (page <a href="#">182</a> )								●	←						● (1)	● (1)	↑		
Fast stop (page <a href="#">182</a> )															● (1)		↑		
Freewheel stop (page <a href="#">182</a> )									←						↑	↑			
+/- speed around a reference (page <a href="#">196</a> )			●	●	●	←	↑												
High speed hoisting (page <a href="#">216</a> )			●	●	●													↑	
Load sharing (page <a href="#">130</a> )			●																
Positioning by sensors (page <a href="#">239</a> )			●																↑

(1) Priority is given to the first of these two stop modes to be activated.

(2) Only the multiplier reference is incompatible with the PID regulator.

Incompatible functions

Compatible functions

Not applicable

Priority functions (functions which cannot be active at the same time):

↑ The function indicated by the arrow has priority over the other.