Title: How to use M200 to control ATV303 via Modbus RTU?

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Apply to:

SoMachine Basic 1.3 SP1 EL build 44557

TM200CE40T, ATV303

Summary:

This document is a quick guide to show you how to use M200 to control ATV303 via Modbus RTU. Including parameter setup, cable connection, and program introduction.

Solution:

1. ATV303 setup

Code	Name	Setting	Function description
401	Reference channel 1	[164]Modbus	Reference channel 1 by Modbus
406	Channel configuration	01	Combined mode
701	Modbus address	4	OFF to 247
702	Modbus baud rate	[32]* 19.2	[24] 4.8 kbps
		κυρε	[28] 9.6 kbps
			[32]19.2 kbps
			[36] 38.4 kbps
703	Modbus format	[03]* 8E1	[02]8O1
			[03]8E1
			[04]8n1
			[05]8n2
704	Modbus time out	10s	The drive detects a Modbus fault if the drive does not receive a Modbus request within a predefined time period

2. Connect Cable

Pin out of the ATV303 RJ45 Connector

M200 PLC



3. M200 PLC Setup

Serial line configuration

 Physical Settings 		Protocol Settings
Device	None *	Protocol Modbus RTU *
Init command		Addressing O Slave Master
Baud rate	19200 -	Response timeout (× 100 ms) 10
Parity	Even *	Time between frames (ms) 10
Data bits	8	
Stop bits	1 *	
Physical medium		
RS-485 RS-232	Polarization Yes •	

4. M200 PLC Program Introduction





CMD=%MW200, Frequency Reference=%MW201, ETA=%MW100 Switch on drive, no fault, ETA=16#0250, drive display NST Execute CMD=16#0006, ETA=16#0231, drive display RDY Execute CMD=16#0007, ETA=16#0233, drive display RDY Execute CMD=16#000F, %MW201=10#0500(50 Hz), ETA=16#0237, drive run Execute CMD=16#0002, ETA=16#xx17, quick stop active